Density estimation by Monte Carlo and randomized quasi-Monte Carlo

Pierre L'Ecuyer

Joint work with Amal Ben Abdellah, Art B. Owen, and Florian Puchhammer



Séminaire au GERAD, Montréal, 27 mars 2019

What this talk is about

Quasi-Monte Carlo (QMC) and randomized QMC (RQMC) methods have been studied extensively for estimating an integral, say $\mathbb{E}[X]$, and for approximating a function from its evaluation at a finite number of points.

How can we use them to estimate the entire distribution of X? Here we will focus on estimating the density of X over $[a, b] \subset \mathbb{R}$.

What this talk is about

Quasi-Monte Carlo (QMC) and randomized QMC (RQMC) methods have been studied extensively for estimating an integral, say $\mathbb{E}[X]$, and for approximating a function from its evaluation at a finite number of points.

How can we use them to estimate the entire distribution of X? Here we will focus on estimating the density of X over $[a, b] \subset \mathbb{R}$.

People often look at empirical distributions via histograms, for example. More refined methods: kernel density estimators (KDEs). Can RQMC improve such density estimators, and by how much?

Are there other types of density estimators than KDEs, that work better with RQMC?

What this talk is about

Quasi-Monte Carlo (QMC) and randomized QMC (RQMC) methods have been studied extensively for estimating an integral, say $\mathbb{E}[X]$, and for approximating a function from its evaluation at a finite number of points.

How can we use them to estimate the entire distribution of X? Here we will focus on estimating the density of X over $[a, b] \subset \mathbb{R}$.

People often look at empirical distributions via histograms, for example. More refined methods: kernel density estimators (KDEs). Can RQMC improve such density estimators, and by how much?

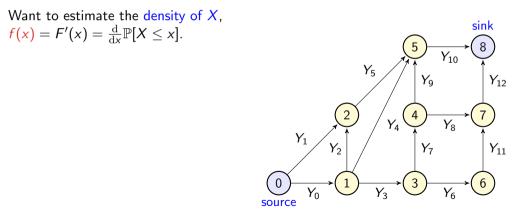
Are there other types of density estimators than KDEs, that work better with RQMC?

We will discuss an alternative that takes the sample derivative of a smoothed estimator of the cumulative distribution function (cdf). The smoothing can be achieved via conditional Monte Carlo, for example.

Small example: A stochastic activity network

Gives precedence relations between activities. Activity k has random duration Y_k (also length of arc k) with known cdf $F_k(y) := \mathbb{P}[Y_k \leq y]$.

Project duration X = (random) length of longest path from source to sink.



Small example: A stochastic activity network

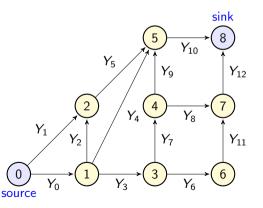
Gives precedence relations between activities. Activity k has random duration Y_k (also length of arc k) with known cdf $F_k(y) := \mathbb{P}[Y_k \leq y]$.

Project duration X = (random) length of longest path from source to sink.

Want to estimate the density of X, $f(x) = F'(x) = \frac{d}{dx} \mathbb{P}[X \le x].$

The sample cdf $\hat{F}_n(x) = \frac{1}{n} \sum_{i=1}^n \mathbb{I}[X_i \le x]$ is an unbiased estimator of the cdf

 $F(x) = \mathbb{P}[X \leq x].$



Small example: A stochastic activity network

Gives precedence relations between activities. Activity k has random duration Y_k (also length of arc k) with known cdf $F_k(y) := \mathbb{P}[Y_k \leq y]$.

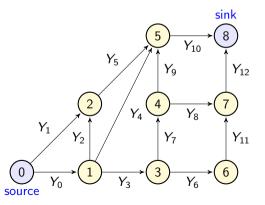
Project duration X = (random) length of longest path from source to sink.

Want to estimate the density of X, $f(x) = F'(x) = \frac{d}{dx} \mathbb{P}[X \le x].$

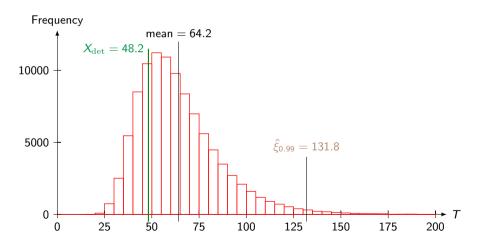
The sample cdf $\hat{F}_n(x) = \frac{1}{n} \sum_{i=1}^n \mathbb{I}[X_i \le x]$ is an unbiased estimator of the cdf $F(x) = \mathbb{P}[X \le x]$

 $F(x) = \mathbb{P}[X \leq x].$

But its derivative $\hat{F}'_n(x)$ is not a meaningful estimator of f(x), because it is 0 almost everywhere.



Numerical illustration from Elmaghraby (1977): $Y_k \sim N(\mu_k, \sigma_k^2)$ for k = 0, 1, 3, 10, 11, and $Y_k \sim \text{Expon}(1/\mu_k)$ otherwise. μ_0, \ldots, μ_{12} : 13.0, 5.5, 7.0, 5.2, 16.5, 14.7, 10.3, 6.0, 4.0, 20.0, 3.2, 3.2, 16.5. Results of an experiment with $n = 100\,000$.



Setting

Classical density estimation was developed in the context where independent observations X_1, \ldots, X_n of X are given and one wishes to estimate the density f of X from that.

Here we assume that X_1, \ldots, X_n are **generated by simulation** from a stochastic model. We can choose *n* and we have some freedom on how the simulation is performed.

The X_i 's are realizations of a random variable $X = g(\mathbf{U}) \in \mathbb{R}$ with density f, where $\mathbf{U} = (U_1, \ldots, U_s) \sim U(0, 1)^s$ and $g(\mathbf{u})$ can be computed easily for any $\mathbf{u} \in (0, 1)^s$.

Can we obtain a better estimate of f with RQMC instead of MC? How much better? Whats about taking a stratified sample over $[0, 1)^{s}$?

Density Estimation

Suppose we estimate the density f over a finite interval [a, b]. Let $\hat{f}_n(x)$ denote the density estimator at x, with sample size n. We use the following measures of error:

$$\begin{split} \text{MISE} &= \text{ mean integrated squared error} = \int_{a}^{b} \mathbb{E}[(\hat{f}_{n}(x) - f(x))^{2}] \mathrm{d}x \\ &= \text{IV} + \text{ISB} \\ \text{IV} &= \text{ integrated variance} = \int_{a}^{b} \text{Var}[\hat{f}_{n}(x)] \mathrm{d}x \\ \text{ISB} &= \text{ integrated squared bias} = \int_{a}^{b} (\mathbb{E}[\hat{f}_{n}(x)] - f(x))^{2} \mathrm{d}x \end{split}$$

Density Estimation

Simple histogram: Partition [a, b] in *m* intervals of size h = (b - a)/m and define

$$\hat{f}_n(x) = \frac{n_j}{nh}$$
 for $x \in I_j = [a + (j-1)h, a + jh), j = 1, ..., m$

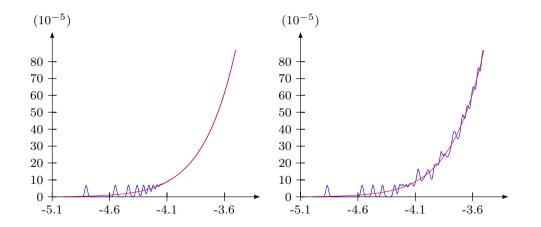
where n_j is the number of observations X_i that fall in interval j.

Kernel Density Estimator (KDE) : Select kernel k (unimodal symmetric density centered at 0) and bandwidth h > 0 (horizontal stretching factor for the kernel). The KDE is

$$\hat{f}_n(x) = \frac{1}{nh} \sum_{i=1}^n k\left(\frac{x-X_i}{h}\right)$$

KDE bandwidth selection: an illustration in s = 1 dimension

KDE (blue) vs true density (red) with RQMC point sets with $n = 2^{19}$: lattice + shift (left), Stratified sample of U = F(X) (right)



Asymptotic convergence with Monte Carlo for smooth *f*

For any $g:\mathbb{R}\to\mathbb{R}$, define

$$\begin{aligned} R(g) &= \int_a^b (g(x))^2 \mathrm{d}x, \\ \mu_r(g) &= \int_{-\infty}^\infty x^r g(x) \mathrm{d}x, \quad \text{ for } r = 0, 1, 2, \dots \end{aligned}$$

For histograms and KDEs, when $n \to \infty$ and $h \to 0$:

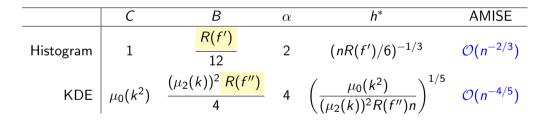
AMISE =
$$AIV + AISB \sim \frac{C}{nh} + Bh^{\alpha}$$
.

| | С | В | α |
|-----------|--------------|---------------------------------|----------|
| Histogram | 1 | $\frac{R(f')}{12}$ | 2 |
| KDE | $\mu_0(k^2)$ | $(\mu_2(k))^2 \frac{R(f'')}{4}$ | 4 |

The asymptotically optimal h is

$$h^* = \left(\frac{C}{B\alpha n}\right)^{1/(\alpha+1)}$$

and it gives $AMISE = Kn^{-\alpha/(1+\alpha)}$.



To estimate h^* , one can estimate R(f') and R(f'') via KDE (plugin). This is under the simplifying assumption that h must be the same all over [a, b].

Elementary quasi-Monte Carlo (QMC) Bounds (Recall) Integration error for $g : [0,1)^s \to \mathbb{R}$ with point set $P_n = \{\mathbf{u}_0, \dots, \mathbf{u}_{n-1}\} \subset [0,1)^s$:

 $\boldsymbol{E}_n = \frac{1}{n} \sum_{i=0}^{n-1} g(\mathbf{u}_i) - \int_{[0,1)^s} g(\mathbf{u}) \mathrm{d}\mathbf{u}.$

Koksma-Hlawka inequality: $|E_n| \leq V_{HK}(g)D^*(P_n)$ where

$$V_{\rm HK}(g) = \sum_{\emptyset \neq v \subseteq S} \int_{[0,1)^s} \left| \frac{\partial^{|v|}g}{\partial v}(\mathbf{u}) \right| d\mathbf{u}, \qquad ({\rm Hardy-Krause} ({\rm HK}) \text{ variation})$$
$$D^*(P_n) = \sup_{\mathbf{u} \in [0,1)^s} \left| \operatorname{vol}[\mathbf{0},\mathbf{u}) - \frac{|P_n \cap [\mathbf{0},\mathbf{u})|}{n} \right| \qquad ({\rm star-discrepancy}).$$

There are explicit point sets for which $D^*(P_n) = \mathcal{O}((\log n)^{s-1}/n) = \mathcal{O}(n^{-1+\epsilon}), \quad \forall \epsilon > 0.$ Explicit RQMC constructions for which $\mathbb{E}[E_n] = 0$ and $\operatorname{Var}[E_n] = \mathcal{O}(n^{-2+\epsilon}), \quad \forall \epsilon > 0.$ With ordinary Monte Carlo (MC), one has $\operatorname{Var}[E_n] = \mathcal{O}(n^{-1}).$

Asymptotic convergence of KDE with RQMC Idea: Replace U_1, \ldots, U_n by RQMC points.

RQMC does not change the bias.

For a KDE with smooth k, one could hope (perhaps) to get

AIV = $C' n^{-\beta} h^{-1}$ for $\beta > 1$, instead of $C n^{-1} h^{-1}$.

If the IV is reduced, the optimal h can be taken smaller to reduce the ISB as well (re-balance) and then reduce the MISE.

Asymptotic convergence of KDE with RQMC Idea: Replace U_1, \ldots, U_n by RQMC points.

RQMC does not change the bias.

For a KDE with smooth k, one could hope (perhaps) to get

 $AIV = C'n^{-\beta}h^{-1} \text{ for } \beta > 1, \text{ instead of } Cn^{-1}h^{-1}.$

If the IV is reduced, the optimal h can be taken smaller to reduce the ISB as well (re-balance) and then reduce the MISE.

Unfortunately, things are not so simple.

Roughly, decreasing h increases the variation of the function in the KDE estimator. So we rather have something like

$$AIV = C' n^{-\beta} h^{-\delta}$$

or $IV \approx C' n^{-\beta} h^{-\delta}$ in some bounded region, for $\beta > 1$ and $\delta > 1$.

Bounding the AIV under RQMC for a KDE

KDE density estimator at a single point *x*:

$$\hat{f}_n(x) = \frac{1}{n} \sum_{i=1}^n \left| \frac{1}{h} k\left(\frac{x - g(\mathbf{U}_i)}{h} \right) \right| = \frac{1}{n} \sum_{i=1}^n \tilde{g}(\mathbf{U}_i).$$

With RQMC points \mathbf{U}_i , this is an RQMC estimator of $\mathbb{E}[\tilde{g}(\mathbf{U})] = \int_{[0,1)^s} \tilde{g}(\mathbf{u}) d\mathbf{u} = \mathbb{E}[\hat{f}_n(x)]$. RQMC does not change the bias, but may reduce $\operatorname{Var}[\hat{f}_n(x)]$, and then the IV. To get RQMC variance bounds, we need bounds on the variation of \tilde{g} .

Bounding the AIV under RQMC for a KDE

KDE density estimator at a single point *x*:

$$\hat{f}_n(x) = \frac{1}{n} \sum_{i=1}^n \left| \frac{1}{h} k\left(\frac{x - g(\mathbf{U}_i)}{h} \right) \right| = \frac{1}{n} \sum_{i=1}^n \tilde{g}(\mathbf{U}_i).$$

With RQMC points \mathbf{U}_i , this is an RQMC estimator of $\mathbb{E}[\tilde{g}(\mathbf{U})] = \int_{[0,1)^s} \tilde{g}(\mathbf{u}) d\mathbf{u} = \mathbb{E}[\hat{f}_n(x)]$. RQMC does not change the bias, but may reduce $\operatorname{Var}[\hat{f}_n(x)]$, and then the IV. To get RQMC variance bounds, we need bounds on the variation of \tilde{g} . The partial derivatives are:

$$rac{\partial^{|\mathfrak{v}|}}{\partial \mathsf{u}_\mathfrak{v}} \widetilde{g}(\mathsf{u}) = rac{1}{h} rac{\partial^{|\mathfrak{v}|}}{\partial \mathsf{u}_\mathfrak{v}} k\left(rac{x-g(\mathsf{u})}{h}
ight).$$

We assume they exist and are uniformly bounded. E.g., Gaussian kernel k. By expanding via the chain rule, we obtain terms in h^{-j} for j = 2, ..., |v| + 1. One of the term for v = S grows as $h^{-s-1}k^{(s)}((g(\mathbf{u}) - x)/h)\prod_{j=1}^{s} g_j(\mathbf{u}) = \mathcal{O}(h^{-s-1})$ when $h \to 0$, so this AIV bound grows in h as h^{-2s-2} . Not so good!

Improvement by a Change of Variable, in One Dimension

Suppose $g : [0,1] \to \mathbb{R}$ is monotone. Change of variable w = (x - g(u))/h. In one dimension (s = 1), we have dw/du = -g'(u)/h, so

$$V_{\rm HK}(\tilde{g}) = \frac{1}{h} \int_0^1 k' \left(\frac{x - g(u)}{h} \right) \left(\frac{-g'(u)}{h} \right) du = \frac{1}{h} \int_{-\infty}^\infty k'(w) dw = \mathcal{O}(h^{-1}).$$

Then, if k and g are continuously differentiable, with RQMC points having $D^*(P_n) = O(n^{-1+\epsilon})$, we obtain AIV = $O(n^{-2+\epsilon}h^{-2})$.

With $h = \Theta(n^{-1/3})$, this gives $AMISE = \mathcal{O}(n^{-4/3+\epsilon})$.

Higher Dimensions

Assumptions. Let $g : [0,1]^s \to \mathbb{R}$ be piecewise monotone in each coordinate u_j when the other coordinates are fixed, with at most M_j pieces. Assume that all first-order partial derivatives of g are continuous and that $\|g_{\mathfrak{W}_1}g_{\mathfrak{W}_2}\cdots g_{\mathfrak{W}_\ell}\|_1 < \infty$ for all selections of non-empty, mutually disjoint index sets $\mathfrak{W}_1, \ldots, \mathfrak{W}_\ell \subseteq S = \{1, \ldots, s\}$.

For each
$$j \in \mathcal{S}$$
, let $G_j = \left\| \prod_{\ell \in \mathcal{S} \setminus \{j\}} g_{\{\ell\}} \right\|_1$ and $c_j = M_j \, \|k^{(s)}\|_\infty \left(G_j + \mathbb{I}(s=2) \, \|g_{\{1,2\}}\|_1 \right)$.

Proposition Then the Hardy-Krause variation of \tilde{g} satisfies

$$V_{
m HK}(ilde{g}) \leq c_j h^{-s} + \mathcal{O}(h^{-s+1}) \qquad ext{for each } j.$$

Corollary. With RQMC point sets having $D^*(P_n) = \mathcal{O}(n^{-1+\epsilon})$ for all $\epsilon > 0$ when $n \to \infty$, using KH and squaring gives the bound

$$\operatorname{AIV} = \mathcal{O}(n^{-2+\epsilon}h^{-2s}) \quad \text{ for all } \epsilon > 0.$$

By picking *h* to minimize the AMISE bound, we obtain $AMISE = O(n^{-4/(2+s)+\epsilon})$. Worst than MC when s > 3. The factor h^{-2s} hurts! But this is only an upper bound.

Stratification of the unit cube

Partition $[0,1)^s$ into $n = b^s$ congruent cubic cells $S_i := \prod_{j=1}^s [i_j/b, (i_j+1)/b)$, $i \in I = \{i = (i_1, i_2, \dots, i_s) : 0 \le i_j < b \text{ for each } j\}$, for some $b \ge 2$.

Construct $P_n = \{\mathbf{U}_1, \dots, \mathbf{U}_n\}$ by sampling one point uniformly in each subcube S_i , independently, and put $X_i = g(\mathbf{U}_i)$ for $i = 1, \dots, n$.

Proposition. Suppose g is monotone. Then the KDE obtained from those points has

$$IV \le (b-a)s \cdot k^2(0) \cdot h^{-2}n^{-(s+1)/s}$$

Corollary. By taking $h = \kappa n^{-(s+1)/(6s)}$, one has $AMISE = \mathcal{O}(n^{-(2/3)(s+1)/s})$.

This gives a better rate than MC for s < 4. The factor h^{-2} hurts, but much less than h^{-2s} .

Empirical Evaluation with Linear Model in a limited region

Regardless of the asymptotic bounds, the true IV and MISE may behave better than for MC for pairs (n, h) of interest. In a region of interest, we consider the model

MISE =
$$|V + |SB| \approx Cn^{-\beta}h^{-\delta} + Bh^{\alpha}$$
.

The optimal h for this model satisfies

$$h^{lpha+\delta}=rac{\mathsf{C}\delta}{Blpha}n^{-eta}.$$

and it gives MISE $\approx K n^{-\alpha\beta/(\alpha+\delta)}$.

We can take the asymptotic α (known) and B (estimated as for MC).

To estimate C, β , and δ , estimate the IV over a grid of values of (n, h), and fit a linear regression model:

$$\log IV \approx \log C - \beta \log n - \delta \log h.$$

Model estimation

For each (n, h), we estimate the IV by making $n_r = 100$ indep. replications of the RQMC density estimator, compute the variance at $n_e = 1024$ evaluation points (stratified) over [a, b], and multiply by (b - a)/n. We use logs in base 2, since n is a power of 2.

Validation

After estimating model parameters, we can test out-of-sample with independent simulation experiments at pairs (n, h) with $h = \hat{h}_*(n)$.

For test cases in which density is known, to assess what RQMC can achieve, we can compute a MISE estimate at those pairs (n, h), and obtain new parameter estimates \tilde{K} and $\tilde{\nu}$ of model MISE $\approx K n^{-\nu}$.

Numerical illustrations

RQMC Point sets:

- MC: Independent points (Crude Monte Carlo),
- Stratification: stratified unit cube,
- LMS: Sobol' points with left matrix scrambling (LMS) + digital random shift,
- NUS: Sobol' points with nested uniform scrambling.

Simple test example with standard normal density

Let Z_1, \ldots, Z_s i.i.d. standard normal generated by inversion, and

$$\boldsymbol{X} = \frac{Z_1 + \dots + Z_s}{\sqrt{s}}.$$

Then $X \sim \mathcal{N}(0, 1)$.

Here we can estimate IV, ISB, and MISE accurately. We can compute $\int_a^b f''(x) dx$ exactly.

We take [a, b] = [-2, 2].

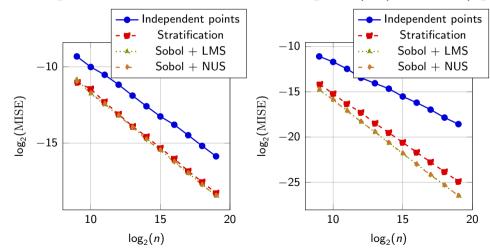
Estimates of model parameters for KDE

ISB =
$$Bh^{\alpha}$$
, IV $\approx Cn^{-\beta}h^{-\delta}$, MISE $\approx \kappa n^{-\nu}$

We have $\alpha = 4$ and B = 0.04754.

| method | MC | Sobol + NUS | | | | |
|---------------|-------|-------------|-------|-------|-------|-------|
| S | 1 | 1 | 2 | 3 | 5 | 20 |
| R^2 | 0.999 | 0.999 | 1.000 | 0.995 | 0.979 | 0.993 |
| eta | 1.017 | 2.787 | 2.110 | 1.788 | 1.288 | 1.026 |
| δ | 1.144 | 2.997 | 3.195 | 3.356 | 2.293 | 1.450 |
| α | 3.758 | 3.798 | 3.846 | 3.860 | 3.782 | 3.870 |
| $\tilde{\nu}$ | 0.770 | 1.600 | 1.172 | 0.981 | 0.827 | 0.730 |
| e19 | 16.96 | 34.05 | 24.37 | 20.80 | 17.91 | 17.07 |

For $n = 2^{19}$, we have MISE $\approx 2^{-e19}$.



Convergence of the MISE, for s = 2, for histograms (left) and KDE (right).

Displacement of a cantilever beam (Bingham 2017)

Displacement D of a cantilever beam with horizontal load X and vertical load Y:

$$D = \frac{4L^3}{Ewt}\sqrt{\frac{Y^2}{t^4} + \frac{X^2}{w^4}}$$

where L = 100, w = 4, t = 2 (in inches), X, Y, and E are independent and normally distributed with means and standard deviations:

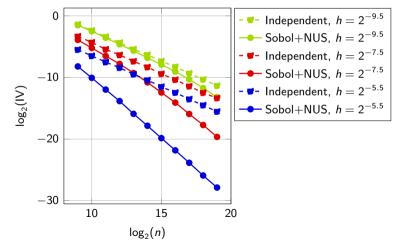
| Description | Symbol | Mean | St. dev. |
|-----------------|--------|----------------|-------------------|
| Young's modulus | Ε | $2.9	imes10^7$ | $1.45	imes10^{6}$ |
| Horizontal load | X | 500 | 100 |
| Vertical load | Y | 1000 | 100 |

We want to estimate the density of $\tilde{X} = D/2.2535 - 1$ over [a, b] = [0.336, 1.561] (about 99.5% of density). Parameter estimates of the linear regression model for IV and MISE:

 $\mathrm{IV} \approx C n^{-\beta} h^{-\delta}, \qquad \qquad \mathrm{MISE} \approx \kappa n^{-\nu}$

| Point set | Ĉ | \hat{eta} | $\hat{\delta}$ | $\hat{\nu}$ | |
|--|---------|-------------|----------------|-------------|--|
| KDE with Gaussian kernel, $\alpha = 4$ | | | | | |
| Independent | 0.210 | 0.993 | 1.037 | 0.789 | |
| $Sobol{+}LMS$ | 5.28E-4 | 1.619 | 2.949 | 0.932 | |
| $Sobol{+}NUS$ | 5.24E-4 | 1.621 | 2.955 | 0.932 | |





A weighted sum of lognormals, in s = 12 dimensions

$$X = \sum_{j=1}^{s} w_j \exp(Y_j)$$

where $\mathbf{Y} = (Y_1, \dots, Y_s)^{\mathrm{t}} \sim \mathcal{N}(\boldsymbol{\mu}, \mathbf{C}).$

Let $\mathbf{C} = \mathbf{A}\mathbf{A}^{\mathrm{t}}.$ To generate \mathbf{Y} , generate $\mathbf{Z} \sim \mathcal{N}(\mathbf{0},\mathbf{I})$ and put $\mathbf{Y} = \boldsymbol{\mu} + \mathbf{A}\mathbf{Z}.$

We will use principal component decomposition (PCA).

This has several applications. In one of them, with $w_j = s_0(s - j + 1)/s$, $e^{-\rho} \max(X - K, 0)$ is the payoff of a financial option based on an average price at s observation times, under a GBM process. Want to estimate density of positive payoffs.

A weighted sum of lognormals, in s = 12 dimensions

$$\boldsymbol{X} = \sum_{j=1}^{s} w_j \exp(Y_j)$$

where $\mathbf{Y} = (Y_1, \dots, Y_s)^{\mathsf{t}} \sim \mathcal{N}(\boldsymbol{\mu}, \mathbf{C}).$

Let $\mathbf{C} = \mathbf{A}\mathbf{A}^{\mathsf{t}}.$ To generate \mathbf{Y} , generate $\mathbf{Z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$ and put $\mathbf{Y} = \boldsymbol{\mu} + \mathbf{A}\mathbf{Z}.$

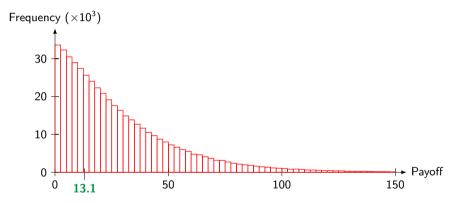
We will use principal component decomposition (PCA).

This has several applications. In one of them, with $w_j = s_0(s - j + 1)/s$, $e^{-\rho} \max(X - K, 0)$ is the payoff of a financial option based on an average price at s observation times, under a GBM process. Want to estimate density of positive payoffs.

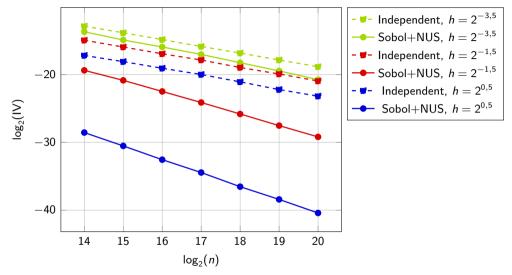
Numerical experiment: Take s = 12, $\rho = 0.037$, $s_0 = 100$, K = 101, and **C** defined indirectly via: $Y_j = Y_{j-1}(\mu - \sigma^2)j/s + \sigma B(j/s)$ where $Y_0 = 0$, $\sigma = 0.12136$, $\mu = 0.1$, and $B(\cdot)$ a standard Brownian motion.

We will estimate the density of $e^{-\rho}(X - K)$ over [a, b] = [0, 50].

Histogram of positive values from $n = 10^6$ independent simulation runs:



IV as a function of *n* for fixed *h*, for KDE.



The RQMC bound in s = 12 dimension gives a worst rate than MC, but we observe a better actual IV and MISE.

Alternative approach:

Can we take the stochastic derivative of an estimator of F?

Can we estimate the density f(x) = F'(x) by the derivative w.r.t. x of an estimator of F(x). A simple candidate cdf estimator is the empirical cdf

$$\hat{\mathcal{F}}_n(x) = \frac{1}{n} \sum_{i=1}^n \mathbb{I}[X_i \leq x].$$

However $d\hat{F}_n(x)/dx = 0$ almost everywhere, so this cannot be a useful density estimator! We need a smoother estimator of F.

Conditional Monte Carlo (CMC) for Derivative Estimation

Idea: Replace the indicator $\mathbb{I}[X_i \leq x]$ by its conditional cdf given filtered (reduced) information \mathcal{G} :

$$F(x \mid \mathcal{G}) := \mathbb{P}[X \le x \mid \mathcal{G}]$$

where the sigma-field \mathcal{G} contains not enough information to reveal X but enough to compute $F(x \mid \mathcal{G})$, and is chosen so that the following holds:

Conditional Monte Carlo (CMC) for Derivative Estimation

Idea: Replace the indicator $\mathbb{I}[X_i \leq x]$ by its conditional cdf given filtered (reduced) information \mathcal{G} :

$$F(x \mid \mathcal{G}) := \mathbb{P}[X \le x \mid \mathcal{G}]$$

where the sigma-field \mathcal{G} contains not enough information to reveal X but enough to compute $F(x \mid \mathcal{G})$, and is chosen so that the following holds:

Assumption 1. For all realizations of \mathcal{G} , $F(x | \mathcal{G})$ is a continuous function of x which is differentiable except perhaps over a denumerable set of points, and for which the derivative $F'(x | \mathcal{G}) = dF(x | \mathcal{G})/dx$ (when it exists), which is itself a random variable for each x, is bounded uniformly in x by some random variable Γ having finite variance.

Theorem: F'(x | G) is an unbiased estimator of f(x), with variance bounded uniformly in x.

Overall estimator with *n* iid replicates: $\hat{f}_{cmc,n}(x) = \frac{1}{n} \sum_{i=1}^{n} F'(x \mid G_i).$

With this estimator, $\mathrm{ISB}=0,$ so $\mathrm{MISE}=\mathrm{IV},$ which is rather easy to estimate.

The idea was introduced by Asmussen (2018) for a sum of random variables.

Application to the normalized sum of standard normals We had

$$X = \frac{Z_1 + Z_2 + \dots + Z_s}{\sqrt{s}}$$

where each $Z_j \sim \mathcal{N}(0,1)$. For CMC, we can leave out Z_s , so $\mathcal{G} = (Z_1,\ldots,Z_{s-1})$ and

$$\begin{aligned} F(x \mid \mathcal{G}) &= & \mathbb{P}[X \leq x \mid Z_1, \dots, Z_{s-1}] = \mathbb{P}[Z_s \leq x\sqrt{s} - (Z_1 + Z_2 + \dots + Z_{s-1})] \\ &= & \Phi(x\sqrt{s} - (Z_1 + Z_2 + \dots + Z_{s-1})). \end{aligned}$$

The resulting density estimator is

$$F'(x \mid \mathcal{G}) = \phi(x\sqrt{s} - (Z_1 + Z_2 + \cdots + Z_{s-1}))\sqrt{s}.$$

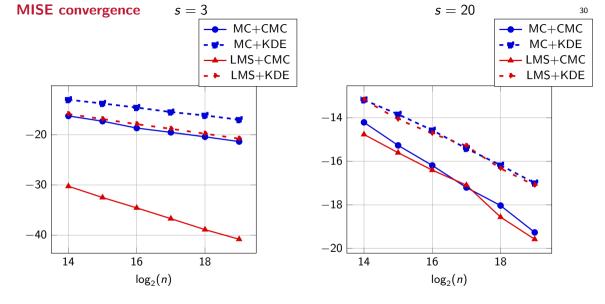
Assumption 1 is easily verified.

| | | <i>s</i> = 3 | | | s = 20 | | |
|-----|-----|--------------|---------------|-----------|--------|---------------|-----------|
| | | MC | $Sobol{+}LMS$ | Sobol+NUS | MC | $Sobol{+}LMS$ | Sobol+NUS |
| СМС | ν | 1.019 | 2.116 | 2.094 | 0.988 | 0.961 | 0.982 |
| | e19 | 21.36 | 40.81 | 40.65 | 19.27 | 19.58 | 19.54 |
| KDE | ν | 0.798 | 0.976 | 0.975 | 0.769 | 0.771 | 0.760 |
| | e19 | 17.01 | 20.79 | 20.80 | 17.00 | 17.10 | 17.07 |

For $n = 2^{19}$, we have MISE $\approx 2^{-e19}$.

We see that CMC is always helping, with both MC and RQMC.

CMC+RQMC brings a huge gain in 3 dimensions, much less in 20 dimensions.



Cantilever beam

$$D = \frac{4L^3}{Ewt}\sqrt{\frac{Y^2}{t^4} + \frac{X^2}{w^4}}$$

where *E*, *X*, *Y* are normal r.v.'s. Want density over [a, b] = [0.407, 1.515]. For CMC, we can leave out *E*, i.e., take $\mathcal{G} = (X, Y)$. Then,

$$F(d \mid \mathcal{G}) = \mathbb{P}[D \leq d \mid X, Y] = \mathbb{P}\left[\frac{4L^3}{Ewt}\sqrt{\frac{Y^2}{t^4} + \frac{X^2}{w^4}} \leq d \mid X, Y\right] = 1 - \Phi\left(\frac{\frac{4L^3}{dwt}\sqrt{\frac{Y^2}{t^4} + \frac{X^2}{w^4}} - \mu_E}{\sigma_E}\right)$$

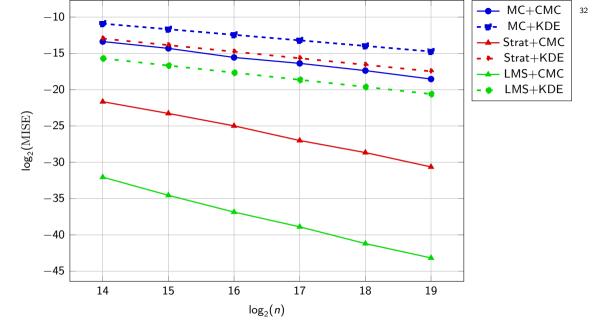
Taking the derivative w.r.t. d, we get

$$F'(d \mid \mathcal{G}) = \phi\left(\frac{\frac{4L^3}{dwt}\sqrt{\frac{Y^2}{t^4} + \frac{X^2}{w^4}} - \mu_E}{\sigma_E}\right) \times \frac{4L^3}{d^2wt\sigma_E}\sqrt{\frac{Y^2}{t^4} + \frac{X^2}{w^4}}.$$

Estimated MISE = $Kn^{-\nu}$.

For $n = 2^{19}$, we have MISE $\approx 2^{-e19}$.

| | | MC | Strat | LMS | NUS |
|-------|-----|----------------------|-------|-------|-------|
| CMC | ν | 1.02 | 1.80 | 2.22 | 2.16 |
| CIVIC | e19 | 1.02 18.54 | 30.64 | 43.18 | 43.08 |
| KDE | ν | 0.81 | 0.89 | 0.94 | 0.96 |
| NDE | e19 | 0.81 15.12 | 18.08 | 21.33 | 21.35 |



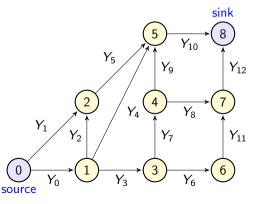
Small example: A stochastic activity network

Gives precedence relations between activities. Activity k has random duration Y_k (also length of arc k) with known cdf $F_k(y) := \mathbb{P}[Y_k \leq y]$.

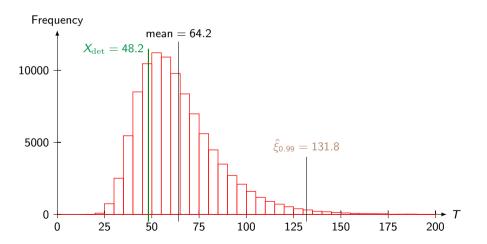
Project duration X = (random) length of longest path from source to sink.

Want to estimate the density of X, $f(x) = F'(x) = \frac{d}{dx} \mathbb{P}[X \le x].$

We saw that $\hat{F}'_n(x)$ is not a meaningful estimator of f(x).



Numerical illustration from Elmaghraby (1977): $Y_k \sim N(\mu_k, \sigma_k^2)$ for k = 0, 1, 3, 10, 11, and $Y_k \sim \text{Expon}(1/\mu_k)$ otherwise. μ_0, \ldots, μ_{12} : 13.0, 5.5, 7.0, 5.2, 16.5, 14.7, 10.3, 6.0, 4.0, 20.0, 3.2, 3.2, 16.5. Results of an experiment with $n = 100\,000$.



The SAN example, Sobol+NUS vs Independent points, KDE, summary for $n = 2^{19} = 524288$.

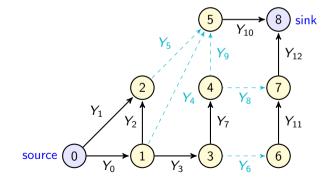
| Density | | Independent points | | Sobol+NUS | |
|---------|------|--------------------|---------|-------------|---------|
| Density | h | $\log_2 IV$ | IV rate | $\log_2 IV$ | IV rate |
| | 0.10 | -16.64 | -0.999 | -16.71 | -1.006 |
| | 0.18 | -17.96 | -0.999 | -18.18 | -1.015 |
| | 0.32 | -19.33 | -0.998 | -19.79 | -1.035 |
| | 0.43 | -19.99 | -0.998 | -20.71 | -1.064 |

CMC for the SAN Example

Want to estimate the density of the longest path length X.

CMC estimator of $\mathbb{P}[X \leq x]$: $F(x \mid \mathcal{G}) = \mathbb{P}[X \leq x \mid \{Y_j, j \notin \mathcal{L}\}]$

where $\mathcal{L} = \{4, 5, 6, 8, 9\}$ and $Y_j = F_j^{-1}(U_j)$. This estimator continuous in the U_j 's and in x.



To compute $F(t | \mathcal{G})$: for each $l \in \mathcal{L}$, say from a_l to b_l , compute the length α_l of the longest path from 1 to a_l , and the length β_l of the longest path from b_l to the destination.

The longest path that passes through link *I* does not exceed *t* iff $\alpha_I + Y_I + \beta_I \leq x$, which occurs with probability $\mathbb{P}[Y_I \leq x - \alpha_I - \beta_I] = F_I[x - \alpha_I - \beta_I]$.

To compute $F(t | \mathcal{G})$: for each $l \in \mathcal{L}$, say from a_l to b_l , compute the length α_l of the longest path from 1 to a_l , and the length β_l of the longest path from b_l to the destination.

The longest path that passes through link *I* does not exceed *t* iff $\alpha_I + Y_I + \beta_I \leq x$, which occurs with probability $\mathbb{P}[Y_I \leq x - \alpha_I - \beta_I] = F_I[x - \alpha_I - \beta_I]$.

Since the Y_l are independent, we obtain

$$F(x \mid G) = \prod_{I \in \mathcal{L}} F_I[x - \alpha_I - \beta_I].$$

To estimate the density of X, take the derivative w.r.t. x:

$$F'(x \mid \mathcal{G}) = \frac{\mathrm{d}}{\mathrm{d}x} F(x \mid \mathcal{G}) \stackrel{\text{w.p.}}{=} \sum_{j \in \mathcal{L}} f_j [x - \alpha_j - \beta_j] \prod_{l \in \mathcal{L}, \ l \neq j} F_l [x - \alpha_l - \beta_l].$$

Assumption 1 holds if the F_j are smooth enough, and then $\mathbb{E}[F'(x \mid G)] = f_X(x)$.

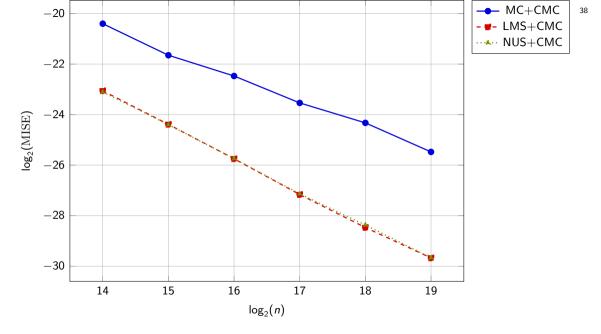
Estimated $MISE = Kn^{-\nu}$, for KDE with CMC.

For $n = 2^{19}$, MISE $\approx 2^{-e19}$.

| | | MC | LMS | NUS |
|-------|-----|-------|-------|-------|
| СМС | ν | 0.99 | 1.34 | 1.32 |
| CIVIC | e19 | 25.48 | 29.67 | 29.66 |

For comparison, the base case without CMC and RQMC gave e19 \approx 20.

With MC, the IV converges as $\mathcal{O}(1/n)$ and there is no bias, so MISE = IV. With RQMC, we observe a convergence rate near $\mathcal{O}(n^{-4/3})$ for the IV and the MISE.



Conclusion

- Both CMC and RQMC can improve the convergence rate of the IV and MISE when estimating a density.
- With KDEs, the convergence rates observed in small examples are much better than the bounds proved from standard QMC theory. There are opportunities for QMC theoreticians here!
- The combination of CMC with RQMC for density estimation is very promising. Lots of potential applications.
- Future: Density estimation for a function of the state of a Markov chain, using Array-RQMC.
- More applications.

Some references

- S. Asmussen. Conditional Monte Carlo for sums, with applications to insurance and finance, Annals of Actuarial Science, prepublication, 1–24, 2018.
- A. Ben Abdellah, P. L'Ecuyer, A. B. Owen, and F. Puchhammer. Density estimation by Randomized Quasi-Monte Carlo. Submitted, 2018.
- J. Dick and F. Pillichshammer. Digital Nets and Sequences: Discrepancy Theory and Quasi-Monte Carlo Integration. Cambridge University Press, Cambridge, U.K., 2010.
- P. L'Ecuyer. A unified view of the IPA, SF, and LR gradient estimation techniques. Management Science 36: 1364–1383, 1990.
- P. L'Ecuyer. Quasi-Monte Carlo methods with applications in finance. Finance and Stochastics, 13(3):307–349, 2009.
- P. L'Ecuyer. Randomized quasi-Monte Carlo: An introduction for practitioners. In P. W. Glynn and A. B. Owen, editors, *Monte Carlo and Quasi-Monte Carlo Methods 2016*, 2017.
- P. L'Ecuyer and G. Perron. On the Convergence Rates of IPA and FDC Derivative Estimators for Finite-Horizon Stochastic Simulations. Operations Research, 42 (4):643–656, 1994.
- A. B. Owen. Scrambled Net Variance for Integrals of Smooth Functions. Annals of Statistics, 25 (4):1541–1562, 1997.
- D. W. Scott. Multivariate Density Estimation. Wiley, 2015.