

today: finish surrogate losses
theory basics

III) structured hinge loss

$$f_{svm}^*(x, y; w) = \max_{\tilde{y} \in \mathcal{Y}(x)} \underbrace{[s(x, \tilde{y}; w) + l(y, \tilde{y})]}_{\text{loss-augmented decoding}} - s(x, y; w)$$

a) cartoon: $\Rightarrow g_{\text{svm}}(x, y; \omega) = 0$

$$b) \mathcal{J}^{\text{sum}}(x, y; \omega) \geq l(y, h_{\omega}(x))$$

why? $f(x, y; \omega) = \max_{\hat{y}} [s(\hat{y}) + l(\hat{y})] - s(y)$ let $\hat{y} = \underset{y}{\operatorname{argmax}} s(y)$

$\geq s(\hat{y}) + l(\hat{y}) - s(y)$

if $y \in \mathcal{F}(x) \rightarrow s(\hat{y}) \geq s(y)$

$\Rightarrow l(\hat{y}) = l(y, \underbrace{h(\omega(x))}_{\hat{y}}) //$

binary case: structured hinge loss reduces to binary SVM loss

$$y \in \{-1, +1\} \quad w = \begin{pmatrix} w_+ \\ w_- \end{pmatrix} \quad \varphi(x, +1) = \begin{pmatrix} \varphi(x) \\ 0 \end{pmatrix}$$

$$h_w(x) = \operatorname{argmax} \{ \langle w_+, \varphi(x) \rangle, \langle w_-, \varphi(x) \rangle \}$$

product +1 if $\langle w_+, \varphi(x) \rangle \geq \langle w_-, \varphi(x) \rangle$

$$\Leftrightarrow \langle \underbrace{w_+ - w_-}, \ell(x) \rangle \geq 0$$

$$\tilde{\omega} \triangleq \omega_+ - \omega_- \quad h_{\omega}(x) = \text{sgn}(\langle \tilde{\omega}, \varphi(x) \rangle)$$

(see notes to show)

structured hinge loss

$$\tilde{w} = w_+ - w_- \quad h_w(x) = \text{sgn}(\langle \tilde{w}, x \rangle)$$

$$\mathcal{L}^{\text{SUM}}(x, y; w) = \max_{w_+ = \tilde{w} + w_-} \left\{ \langle w_+, x \rangle + \underbrace{\ell(y, +)}_{\mathbb{1}\{y \neq +1\}}, \langle w_-, x \rangle + \underbrace{\ell(y, -)}_{1 - \mathbb{1}\{y \neq +1\}} \right\} - \langle w_y, x \rangle$$

$$= \max \left\{ \langle \tilde{w}, x \rangle + \langle w_-, x \rangle + \mathbb{1}\{y \neq +1\}, \langle w_-, x \rangle + 1 - \mathbb{1}\{y \neq +1\} \right\} - \langle w_y, x \rangle$$

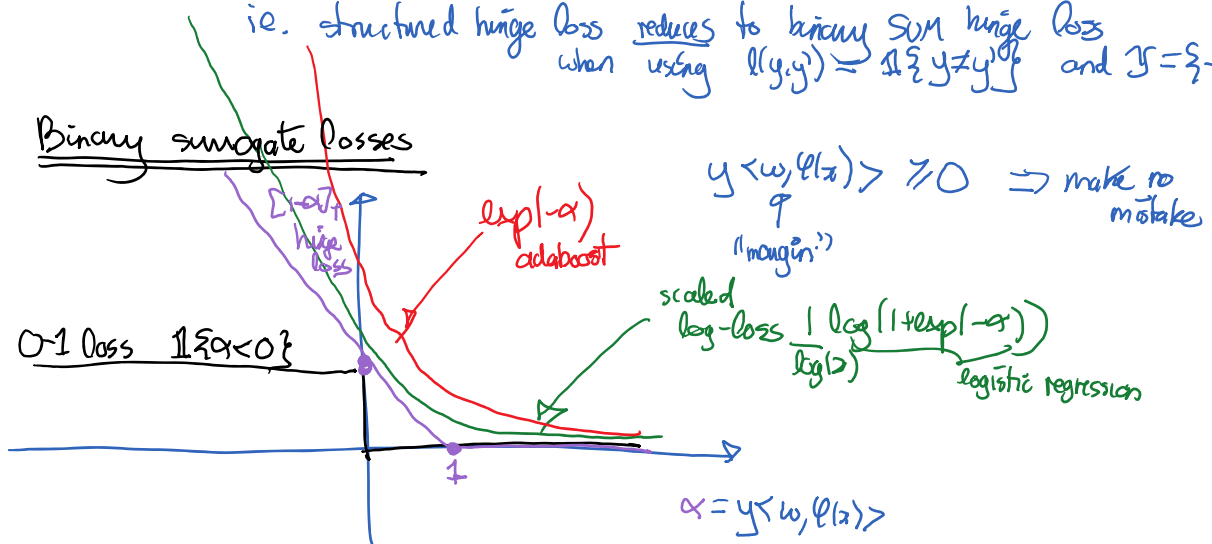
$$= \max \left\{ \langle \tilde{w}, x \rangle + 1, 1 - 1 \right\} + \langle w_-, x \rangle - \langle w_y, x \rangle$$

(case $y = +1$): $\max \{ \langle \tilde{w}, x \rangle, 1 \} - \langle \tilde{w}, x \rangle = [1 - y \langle \tilde{w}, x \rangle]_+$
 (case $y = -1$): $\max \{ \langle \tilde{w}, x \rangle + 1, 0 \} + 0 = [1 - y \langle \tilde{w}, x \rangle]_+$

overall: $[1 - y \langle \tilde{w}, x \rangle]_+$

$$\mathcal{L}^{\text{SUM}}(x, y; w) = [1 - y \langle \tilde{w}, \phi(x) \rangle]_+ \quad \text{where } \tilde{w} \triangleq w_+ - w_-$$

ie. structured hinge loss reduces to binary SUM hinge loss when using $\ell(y, y') = \mathbb{1}\{y \neq y'\}$ and $\mathcal{Y} = \{-1, +1\}$



[Bartlett et al. 2006] $\rightarrow$ showed all these methods are consistent

theory basics

decision theory setup

estimate $h_w: X \rightarrow \mathcal{Y}$

generalization error = $L_P(w) \triangleq \mathbb{E}_{(x,y) \sim P} [\ell(y, h_w(x))]$

task loss

ultimate goal is to find $w^* = \arg\min_{w \in \mathcal{H}} L_P(w)$

ultimate goal is to find $w^* = \underset{w \in W}{\operatorname{argmin}} L_P(w)$

problem: do not know P ("true" distribution on (x, y))

suppose $\underbrace{(x^{(i)}, y^{(i)})}_{\substack{\cong D_n \\ \text{training dataset}}}_{i=1}^n \stackrel{\text{i.i.d.}}{\sim} P \quad \rightarrow \text{we could look at}$
 $\hat{L}_n(w) = \frac{1}{n} \sum_{i=1}^n \ell(y_i^{(D)}, w(x^{(i)}))$

from statistics / prob. theory

$\hat{L}_n(w) \xrightarrow[n \rightarrow \infty]{\text{a.s.}} L_P(w)$ for each fixed w (pointwise)
 (LLN)

this is weaker than $\sup_w |\hat{L}_n(w) - L_P(w)| \xrightarrow{n \rightarrow \infty} 0$

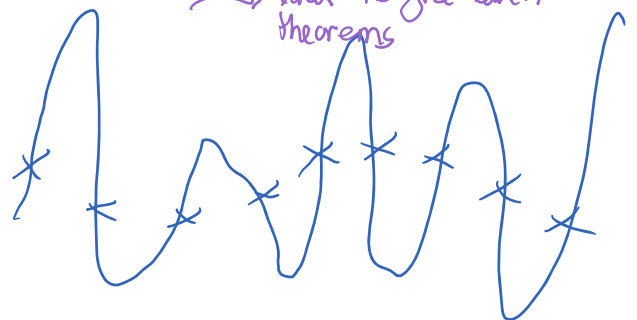
note: minimizing the training error gives no guarantee in general?
 on $L_P(w_n)$

$\rightarrow$ later no free lunch theorems

e.g. polynomial regression

for n points can get zero training error with poly of degree $n-1$

$\Rightarrow$ overfitting



in learning theory: study properties of learning alg. $A: D_n \rightarrow W$

in particular, what can we say about $L_P(A(D_n))$

different approaches:

a) "frequentist risk" $R_{P,n}^F(A) \triangleq \mathbb{E}_{D_n \sim P^n} [L_P(A(D_n))]$ D_n is random

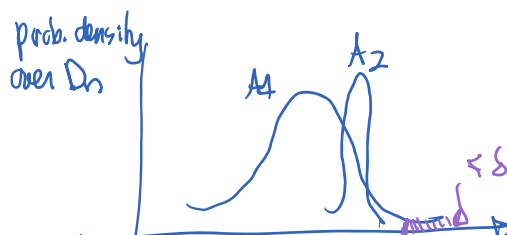
b) PAC framework
 "probably approximately correct"

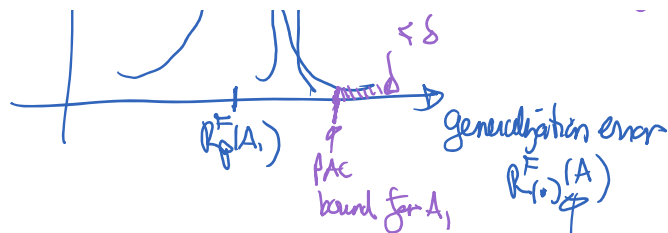
$P\{L_P(A(D_n)) > \text{some bound}\} \leq \delta$

"tail bound"

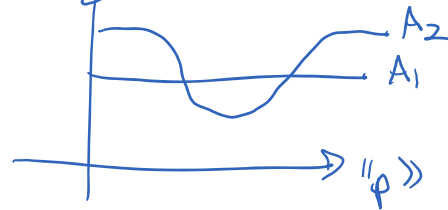
ie. $L_P(A(D_n)) \leq \text{some bound}$ with prob. $\geq 1 - \delta$

$\rightarrow$ generalization error bound





issue with $R_p^F \rightarrow$ depends on P
"risk profiles"



weighted frequentist risk $\mathbb{E}_{\theta \sim \pi(\theta)} [R_{A\theta}^F(A)]$

c) "Bayesian posterior risk"

$$R^{Post}(\omega | D_n) \triangleq \mathbb{E}_{\theta \sim p(\theta | D_n)} [L_\theta(\omega)]$$

Bayesian estimate $\hat{\omega}_n^{Bayes} = \arg \min_{\omega} R^{Post}(\omega | D_n)$

$A^{Bayesian}$ is optimal for weighted frequentist risk using $\pi(\theta) = p(\theta)$

• prior $p(\theta)$ over dist.

• observation model $p(D_n | \theta)$
 $\Rightarrow$ posterior $p(\theta | D_n)$

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no free lunch?

frequentist risk analysis learning alg. A

let $\mathcal{P}$ be a set of distributions on $X \times Y$

sample complexity of A with respect to $\mathcal{P}$

is the smallest $n(\mathcal{P}, A, \epsilon)$ s.t. $\forall n \geq n(\mathcal{P}, A, \epsilon)$

$$\text{we have } \sup_{p \in \mathcal{P}} [R_p^F(A; n) - L_p(h_p^*)] \leq \epsilon$$

"uniform result"

$$h_p^* = \arg \min_{h: X \rightarrow Y} L_p(h)$$

terminology: • A is consistent for dist. p

$$\text{is } \lim_{n \rightarrow \infty} R_p^F(A; n) - L_p(h_p^*) = 0$$

• A is uniformly consistent for a family $\mathcal{P}$

$$\text{is } \lim_{n \rightarrow \infty} \left[\sup_{p \in \mathcal{P}} [R_p^F(A; n) - L_p(h_p^*)] \right] = 0$$

Binary classification $\mathcal{Y} = \{-1, +1\}$

I) if X is finite; then the "voting procedure" (assign the most frequent label to an input x)
 is uniformly and universally consistent
 $\rightarrow$ i.e. $\mathcal{P}$ is all dist. on $X \times \mathcal{Y}$
 with (universal) sample complexity

$$n(\mathcal{P}, \varepsilon, \text{Averaging}) \leq \frac{|X|}{\varepsilon^2} \quad (\text{free lunch?})$$

II) if X is infinite

no free lunch theorem $\exists$ (for binary with ℓ the 0-1 loss)

for any n and any learning alg. A

$$\text{then } \sup_{P \text{ dist.}} [R_P^F(A; n) - L_P(h_P^*)] \geq \frac{1}{2}$$

i.e. $\exists$ always a dist. $P_{A,n}$ s.t. A is worse than random predictor for $P_{A,n}$

NFL II: [Thm. 7.2 in Vapnik & Chervakov 1996]

let ε_n be any non-increasing seq. converging to 0 + $(\varepsilon_n \leq \frac{1}{n})$

for A , then $\exists P_A$ s.t.

$$[R_{P_A}^F(A; n) - L_{P_A}(h_{P_A}^*)] \geq \varepsilon_n \ln n$$

ε_n
 (could be arbitrarily slow
 e.g. $\frac{1}{\lg(\lg(\lg(\dots \ln)))}$)

~~consequence~~ consequence is we need assumption on $\mathcal{P}$ to say anything useful

Occam's generalization error bound

- binary class. & 0-1 loss
- consider W to be a countable set

let's define a prior over W : $\pi(w)$ i.e. $\sum_{w \in W} \pi(w) = 1$ $\pi(w) \geq 0 \forall w$

$|w|_\pi =$ "description length" of $w \triangleq$

$$\log_2 \frac{1}{\pi(w)}$$

$$\sum_w 2^{-|w|_\pi} \leq 1$$

"Kraft's inequality"

Occam's bound

"(11w) Kraft's inequality"

Occam's bound

for any fixed P ; with prob. $\geq 1-\delta$ over training set $D_n \sim P^n$

$$\forall w \in W \quad L_P(w) \leq \hat{L}_P(w) + \frac{1}{\sqrt{2n}} \Omega_\pi(w; \delta)$$

$$\text{where } \Omega_\pi(w; \delta) \triangleq \sqrt{(\ln 2) \underbrace{|w|}_\text{complexity measure} + \ln \frac{1}{\delta}}$$