#### Adaptive Tensor Learning with Tensor Networks

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November 20, 2020 Huawei Montreal research centre

Supervised Learning:

Learn  $f : \mathcal{X} \to \mathcal{Y}$  from a sample  $\{(x_1, y_1), \cdots, (x_N, y_N)\} \subset \mathcal{X} \times \mathcal{Y}$ .

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► Tensor structured data: Images, videos, spatio-temporal data, ...



$$\in \mathbb{R}^{32 \times 32 \times 3} \simeq \mathbb{R}^{3072}$$

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- How to handle input/output structured data?
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  - Discrete structured data: strings, trees, graphs, ...
- In both cases, one can leverage linear and tensor algebra to design learning algorithms.







Tensors



$$\begin{split} \mathbf{M} \in \mathbb{R}^{d_1 \times d_2} & \mathcal{T} \in \mathbb{R}^{d_1 \times d_2 \times d_3} \\ \mathbf{M}_{ij} \in \mathbb{R} \text{ for } i \in [d_1], j \in [d_2] & (\mathcal{T}_{ijk}) \in \mathbb{R} \text{ for } i \in [d_1], j \in [d_2], k \in [d_3] \end{split}$$

# Tensors and Machine Learning

(i) Data has a tensor structure: color image, video, multivariate time series...





(ii) Tensors as parameters of a model: polynomial regression, higher-order RNNs, weighted automata on trees and graphs...



(iii) Tensors as tools: tensor method of moments [Anandkumar et al., 2014], layer compression in neural networks [Novikov et al., 2015], deep learning theoretical analysis [Cohen et al., 2015]...

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#### Tensors are not easy...

#### MOST TENSOR PROBLEMS ARE NP HARD

#### CHRISTOPHER J. HILLAR AND LEK-HENG LIM

ABSTRACT. The idea that one might extend numerical linear algebra, the collection of matrix computational methods that form the workhorse of scientific and engineering computing, to *numeri*cal multilinear algebra, an analogous collection of tools involving hypermatrices/tensors, appears very promising and has attracted a lot of attention recently. We examine here the computational tractability of some core problems in numerical multilinear algebra. We show that tensor analogues of several standard problems that are readily computable in the matrix (i.e. 2-tensor) case are NP hard. Our list here includes: determining the feasibility of a system of bilinear equations, determining an eigenvalue, a singular value, or the spectral norm of a 3-tensor, determining a best rank-1 approximation to a 3-tensor, determining the rank of a 3-tensor over  $\mathbb{R}$  or  $\mathbb{C}$ . Hence making tensor computations feasible is likely to be a challenge.

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... but training a neural network with 3 nodes is also NP hard [Blum and Rivest, NIPS '89]

Forget rows and columns... Now we have fibers!

• Matrices have rows and columns, tensors have fibers<sup>1</sup>:



Fig. 2.1 Fibers of a 3rd-order tensor.

<sup>1</sup>fig. from [Kolda and Bader, *Tensor decompositions and applications*, 2009].

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# Tensors: Multiplication with Matrices







 $\mathbf{AMB}^{\top} \in \mathbb{R}^{m_1 \times m_2}$ 

 $\mathcal{T} imes_1 \mathbf{A} imes_2 \mathbf{B} imes_3 \mathbf{C} \in \mathbb{R}^{m_1 imes m_2 imes m_3}$ 

ex: If  $\mathcal{T} \in \mathbb{R}^{d_1 \times d_2 \times d_3}$  and  $\mathbf{A} \in \mathbb{R}^{m_1 \times d_1}$ ,  $\mathbf{B} \in \mathbb{R}^{m_2 \times d_2}$ ,  $\mathbf{C} \in \mathbb{R}^{m_3 \times d_3}$ , then  $\mathcal{T} \times_1 \mathbf{A} \times_2 \mathbf{B} \times_3 \mathbf{C} \in \mathbb{R}^{m_1 \times m_2 \times m_3}$  is defined by



 $\mathbf{A}\mathbf{M}\mathbf{B}^{ op} \in \mathbb{R}^{m_1 \times m_2}$ 

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$$(\mathcal{T} \times_1 \mathbf{A} \times_2 \mathbf{B} \times_3 \mathbf{C})_{i_1, i_2, i_3} = \sum_{k_1=1}^{n_1} \sum_{k_2=1}^{n_2} \sum_{k_3=1}^{n_3} \mathcal{T}_{k_1 k_2 k_3} \mathbf{A}_{i_1 k_1} \mathbf{B}_{i_2 k_2} \mathbf{C}_{i_3 k_3}$$

for all  $i_1 \in [d_1], i_2 \in [m_2], i_3 \in [d_3]$ .





Matrix product:

$$\underline{m} \land \underline{n} \land \underline{B} \not p \qquad (AB)_{i_1,i_2} = \sum_{k=1}^n A_{i_1k} B_{ki_2}$$



Inner product:

$$\mathbf{u} \quad \mathbf{v} \quad \mathbf{v} = \sum_{k=1}^{n} \mathbf{u}_{k} \mathbf{v}_{k}$$



$$\mathsf{Edge} \equiv \mathsf{contraction}$$

Inner product between tensors:

$$(\mathcal{S}, \mathcal{V}) = \sum_{i_1=1}^{d_1} \sum_{i_2=1}^{d_2} \sum_{i_3=1}^{d_3} \mathcal{S}_{i_1 i_2 i_3} \mathcal{T}_{i_1 i_2 i_3}$$



$$\mathsf{Edge} \equiv \mathsf{contraction}$$

Frobenius norm of a tensor:

$$S \xrightarrow{d_1}_{d_2} S \|S\|_F^2 = \sum_{i_1=1}^{d_1} \sum_{i_2=1}^{d_2} \sum_{i_3=1}^{d_3} (S_{i_1 i_2 i_3})^2$$



Trace of an  $n \times n$  matrix:



 $Tr(\mathbf{M}) = \sum_{i=1}^{n} \mathbf{M}_{ii}$ 





Hyperedge  $\equiv$  contraction between more than 2 indices:



## Multilinear Maps

• Liner map  $f : \mathbb{R}^d \to \mathbb{R}^p$  maps **x** to  $\mathbf{W}\mathbf{x} = \mathbf{W} \times_2 \mathbf{x}$  for some  $\mathbf{W} \in \mathbb{R}^{p \times d}$ :

$$\overset{d}{\mathbf{x}} \mapsto \mathbf{x} \overset{d}{\mathbf{w}}$$

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Multilinear map g: ℝ<sup>d</sup><sub>1</sub> × ℝ<sup>d</sup><sub>2</sub> → ℝ<sup>p</sup> maps (u, v) to W ×<sub>2</sub> u ×<sub>3</sub> v for some W ∈ ℝ<sup>p×d<sub>1</sub>×d<sub>2</sub></sup>:



- Tensors can get huge quickly:
  - 3rd order tensor of shape  $d \times d \times d$ :  $d^3$  parameters
  - ▶ 4th order tensor of shape  $d \times d \times d \times d$ :  $d^4$  parameters
  - ▶ 10th order tensor of shape  $d \times d \times \cdots \times d$ :  $d^{10}$  parameters

**۰**...

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- Similar to matrix factorization:
  - ▶ If  $\mathbf{M} \in \mathbb{R}^{m \times n}$  and  $\mathbf{M} = \mathbf{AB}$  with  $\mathbf{A} \in \mathbb{R}^{m \times r}$  and  $\mathbf{B} \in \mathbb{R}^{r \times n}$

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  - $\Rightarrow$  r(m+n) parameters instead of mn...

• Tucker decomposition [Tucker, 1966]:



 $\Rightarrow$   $R_1R_2R_3 + d_1R_1 + d_2R_2 + d_2R_2$  parameters instead of  $d_1d_2d_3$ .

• Tucker decomposition [Tucker, 1966]:



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• CP decomposition [Hitchcock, 1927]<sup>2</sup>:



<sup>2</sup>fig. from [Kolda and Bader, *Tensor decompositions and applications*, 2009].

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 $\Rightarrow R(d_1 + d_2 + d_3)$  parameters instead of  $d_1 d_2 d_3$ .

<sup>2</sup>fig. from [Kolda and Bader, *Tensor decompositions and applications*, 2009]. Guillaume Rabusseau Adaptive Tensor Learning with Tensor Networ November 20, 2020

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  - If the ranks are all the same (R<sub>1</sub> = R<sub>2</sub> = ··· = R), can represent a vector of size 2<sup>n</sup> with O (nR<sup>2</sup>) parameters!

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  - Inner product, sum, component-wise product, ... all in time linear in n for vectors of size d<sup>n</sup>.

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- We can also efficiently perform operations on TT tensors:
  - Inner product, sum, component-wise product, ... all in time linear in n for vectors of size d<sup>n</sup>.
- Limitations:
  - not all tensors have low TT rank
  - not possible to apply component-wise non-linear functions in the TT format...

• Tensor Ring decomposition [Zhao et al., 2016]:



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#### $\Rightarrow R_4d_1R_1 + R_1d_2R_2 + R_2d_2R_3 + R_3d_4R_4 \text{ parameters instead of } d_1d_2d_3d_4.$

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## Summary of Common Tensor Decomposition Models

- For an *N*th order tensor of size  $d \times d \times d \times \cdots \times d$ , instead of  $d^N$  parameters we have
  - Tucker:  $O(R^N + NdR)$  parameters
  - CP:  $\mathcal{O}(NdR)$  parameters
  - Tensor train (TT):  $O(NdR^2)$  parameters
  - Tensor ring (TR):  $O(NdR^2)$  parameters

where the rank  $R = \max_i R_i$ .

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where the rank  $R = \max_i R_i$ .

- Finding the exact low rank decomposition of a tensor is NP hard for CP but can be done in polynomial time for Tucker and TR
- Low rank approximation problem is NP hard for all decomposition models
- Efficient approximation algorithm exists for the low rank approximation problem

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  - Tensor network methods  $\equiv$  algorithms to efficiently perform operations on (or optimize) very high dimensional objects
- $\Rightarrow$  Lots of interesting open problems and connections with quantum physics and formal languages.
- ⇒ Tensors are the new matrices (linear → multilinear) and tensor networks make it "easy" to reason about tensors, tensor decomposition and multi-linear algebra.

## Outline

1 An Introduction to Tensors and Tensor Networks

2 Adaptive Learning of Tensor Decomposition Models

Joint work with Meraj Hashemizadeh, Michelle Liu and Jacob Miller







• Lots of ways to decompose a tensor:



- $\Rightarrow$  How to choose the *right* decomposition model for a given ML problem?
- $\Rightarrow\,$  Can we design adaptive algorithms, learning the decomposition structure from data?
- $\Rightarrow\,$  What are the different implicit bias encoded in each decomposition model?

 $\Rightarrow$  .

• A lot of tensor problems can be formulated as

$$\min_{oldsymbol{\mathcal{W}}\in\mathbb{R}^{d_1 imes\cdots imes d_p}} L(oldsymbol{\mathcal{W}}) \quad ext{ s.t. rank}(oldsymbol{\mathcal{W}}) \leq R$$

where L is a loss function and rank is some notion of tensor rank (e.g. TT, TR, CP, ...).

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Tensor Decomposition

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Tensor Classification

$$L(\mathcal{W}) = \sum_{i=1}^{N} CCE(y_i, f(\mathcal{X}_i)) \text{ where } f(\mathcal{X}_i) = \operatorname{sign}(\langle \mathcal{W}, \mathcal{X}_i \rangle)$$

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Tensor Completion











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Tensor Completion

$$L(\mathcal{W}) = \sum_{(i,j,k)\in\Omega} (\mathcal{W}_{ijk} - \mathcal{X}_{ijk})^2$$

where  $\boldsymbol{\Omega}$  is the set of observed entries

A greedy algorithm for adaptive learning of TN structures

$$\min_{oldsymbol{\mathcal{W}} \in \mathbb{R}^{d_1 imes \cdots imes d_p}} L(oldsymbol{\mathcal{W}}) \quad ext{ s.t. rank}(oldsymbol{\mathcal{W}}) \leq R$$

- We do not want to assume a fixed decomposition model.
- We want an algorithm that can adaptively find the best decomposition model for the task at hand.

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- We do not want to assume a fixed decomposition model.
- We want an algorithm that can adaptively find the best decomposition model for the task at hand.
- $\hookrightarrow$  We optimize the loss both with respect to the TN structure and the core tensors of the TN:

 $\begin{array}{c} \min \\ \text{Tensor Network Structure TN } \mathcal{G}^{(1)}, \dots, \mathcal{G}^{(p)} \end{array} \mathcal{L}(\mathcal{TN}(\mathcal{G}^{(1)}, \cdots, \mathcal{G}^{(p)})) \\ \text{s.t. size}(\mathcal{G}^{(1)}, \cdots, \mathcal{G}^{(p)}) \leq C \end{array}$ 

A greedy algorithm for adaptive learning of TN structures

$$\begin{array}{c} \min\limits_{\text{Tensor Network Structure TN}} \min\limits_{\mathcal{G}^{(1)}, \cdots, \mathcal{G}^{(p)}} L(\mathcal{TN}(\mathcal{G}^{(1)}, \cdots, \mathcal{G}^{(p)})) \\ \text{s.t. size}(\mathcal{G}^{(1)}, \cdots, \mathcal{G}^{(p)}) \leq C \end{array}$$

- Pbm: the space of TN structures is exponentially large...
- We propose a simple greedy approach:
  - Start with a rank one tensor
  - Optimize the loss wrt the core tensors.
  - Greedily choose an edge to increment in the TN.
  - Repeat until the parameters budget is reached.

• Start with a random rank one tensor.



• Optimize the loss wrt the core tensors.



• Consider all possible rank one increments on internal edges.



• Optimize the loss wrt core tensors for each possible increment.



• Select the most promising rank increment and repeat...



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• Select the most promising rank increment and repeat...



## Implementation Details and Limitations

- At each iteration of greedy, we restart the optimization from the previous solution.
- No internal nodes are added to the initial TN structure (cannot represent Tucker).
- No hyperedge (cannot represent CP).
- Computationally expensive.

### Experiment: Tensor decomposition

- Objective: compress a given tensor (with unknown tensor network structure) by decomposing it.
- Three target tensors of size  $7 \times 7 \times 7 \times 7 \times 7$ :



## Experiment: Tensor decomposition



#### Tensor structures recovered by Greedy



"Triangle" target tensor



Experiment: Tensor completion

#### Original image



Observed pixels



#### $\bullet$ Initial image is reshaped into a 6 $\times$ 10 $\times$ 10 $\times$ 6 $\times$ 10 $\times$ 10 $\times$ 3 tensor

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## **Experiment:** Tensor completion







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### **Experiment:** Tensor completion



#### **Einstein Image Completion**

# **Experiment:** Tensor completion



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Adaptive Tensor Learning with Tensor Netwo

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- First step towards algorithms for general TN rather than specific tensor decomposition models
- Experimental results are very encouraging

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- First step towards algorithms for general TN rather than specific tensor decomposition models
- Experimental results are very encouraging
- Future directions (ongoing):
  - Theory: convergence rate analysis
  - Add support for internal nodes and hyperedges
  - Beyond Greedy:
    - \* develop heuristics for more efficient search
    - ★ backtracking (e.g. A<sup>\*</sup> algorithm)
  - experiments on compressing neural networks

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- Lots of interesting open problems
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  - ► Tensorized Random Projections with Beheshteh T. Rakhshan
  - ► VC dimension of Tensor Network moodels with Behnoush Khavari
  - Connections between tensor networks, RNNs and weighted automata with Tianyu Li, Maude Lizaire, Simon Verret
  - Tensor networks for sequence modeling with Jacob Miller

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# Thank you! Questions?