

## Lecture 6 - generalization error bounds

Thursday, January 25, 2024 9:30 AM

today: generalization error bounds  
structured SVM

generalization error bounds:

for binary classification

a classical PAC bound is:

for any fixed dist  $P$  on data with prob.  $\geq 1-\delta$  on  $D_n$

$$\forall w \in \mathcal{W} \quad L_{\text{01}}(w) \leq \hat{L}_n(w) + \frac{1}{\sqrt{n}} \sqrt{d \log d + \log \frac{1}{\delta}}$$

where  $d$  is the VC-dimension of  $\mathcal{H} = \{h_w : w \in \mathcal{W}\}$

VC-dimension of  $\mathcal{H} \triangleq \max \{m : \exists \text{ a set of } m \text{ points}$

st.  $\mathcal{H}$  labelings of these points

$\exists w \in \mathcal{W}$  s.t.  $h_w$  gives the correct

label on these points

"shattering the set of points"

$$S: I:m \rightarrow \{0,1\}^m$$

note: # of prediction functions on  $m$  points is  $2^m$

for  $\mathcal{H} = \{\text{linear classifiers of } p \text{ parameters}\}$   $\text{VC-dim}(\mathcal{H}) = p+1$

one issue for this bound is that it's true for all distributions  $\Rightarrow$  too loose bound

$\Rightarrow$  motivates going to data distribution dependent measure of complexity

example: empirical Rademacher complexity

$$\hat{R}_{D_n}(\mathcal{H}) \triangleq \mathbb{E}_{\sigma} \left[ \sup_{h_w \in \mathcal{H}} \left| \frac{1}{n} \sum_{i=1}^n \sigma_i \mathbb{1}_{\{y_i \neq h_w(x_i)\}} \right| \right]$$

"correlation with random noise"

iid R.V.  $\sigma_i = \begin{cases} +1 \\ -1 \end{cases}$  "Rademacher" R.V.

bound: with prob.  $\geq 1-\delta$

$$\forall w \quad L_{\text{01}}(w) \leq \hat{L}_n(w) + \hat{R}_{D_n}(\mathcal{H}) + \frac{1}{\sqrt{n}} \sqrt{3 \log \frac{2/\delta}{2}}$$

complexity depends on  $D_n$  (implicitly depends on  $P$ )

structured prediction generalization bounds [Cortes & al. NIPS 2016]

general loss  $\ell(y, y')$  s.t.  $\ell(y, y') \neq 0 \iff y \neq y'$

general loss  $l(y, y')$  s.t.  $l(y, y') \neq 0$   $y \neq y'$

suppose  $s(x, y) = \sum_{c \in C} s_c(x, y_c)$

$C \subseteq \text{set of edges of a graph model } G / \text{factor graph}$

thm. 7 with prob.  $\geq 1 - \delta$

$$\forall w \in W \quad L(w) \leq \hat{L}_{\text{hinge}}(w) + 4\sqrt{2} \hat{R}_{D_n}^G(H_w) + \frac{3}{\sqrt{2n}} \sqrt{\log \frac{1}{\delta}}$$

where  $\hat{R}_{D_n}^G \triangleq \frac{1}{n} \mathbb{E}_O \left[ \sup_{w \in W} \sum_{i=1}^n \sum_{c \in C} \sum_{y_c \in S_c(x_i, y_c; w)} s_c(x_i, y_c; w) \right]$

"empirical factor graph complexity"

actually only depends on  $(x^{(i)})_{i=1}^n$

thm 2 : if  $s_c(x, y_c; w) = \langle w, \ell_c(x, y_c) \rangle$

and consider  $W_L \triangleq \{w : \|w\|_2 \leq L\}$ ; let  $R = \max_{i \in C, j} \|\ell_c(x_i, y_c)\|_2$

then  $\hat{R}_{D_n}^G(H_{W_L}) \leq \frac{R}{\sqrt{n}} |C| \sqrt{\max_{i \in C} \sum_{j \in J_i} \ell_c(x_i, y_c)^2}$

so want small degrees  $\Rightarrow$

\* plug thm. 2 back in thm. 7

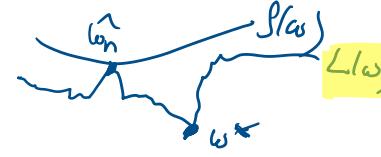
$$L(w) \leq \hat{L}_{\text{hinge}}(w) + \left( \frac{R |C| \sqrt{\max_{i \in C} \sum_{j \in J_i} \ell_c(x_i, y_c)^2}}{\sqrt{n}} \right) \|w\|_2 + \text{const.}$$

min of R.H.S. suggests

$$\text{SVM struct alg. } \hat{w}_n = \underset{w}{\operatorname{arg\,min}} \hat{L}_{\text{hinge}}(w) + \frac{\lambda n}{2} \|w\|_2^2$$

- missing link:
- ①  $\min_{\|w\|_2 \leq L} f(w)$  (if  $f$  is convex) use Lagrangian duality  
s.t.  $\|w\|_2^2 \leq L^2$
  - ②  $\min f(w) + \frac{\lambda}{2} \|w\|_2^2$  s.t. to ② gives same solution to ①

[Side note: constrained formulation can have solutions not achievable for ② when  $f$  is non-convex]  
best penalized/reg. formulation is less sensitive to choice of  $\lambda$  vs. constrained formulation

- (10h26) can think of SVMstruct as minimizing an upper bound on  $L(\omega)$ .  
 properties:
- minimize upper bound, hope that  $\min L(\omega)$
  - but no general guarantees
  - can evaluate bound to get guarantees
- Caveat: also note here: no consistency guarantee
- 

next: consistency + convex surrogates

### consistency & calibration

need to relate  $g(\omega)$  to  $L(\omega)$ ; b/c "calibration fn." [Steinwart]

relationship is usually very complicated

$\Rightarrow$  classical results look mainly at non-parametric setting (no # of parameters)

all functions  $h: X \rightarrow \mathbb{Y}$  are considered  $\Rightarrow$  this evaluates the dependence on  $x$  of the analysis  
 "partwise analysis")

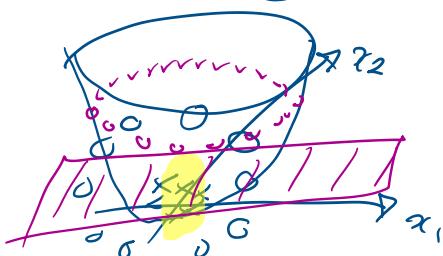
i.e. we suppose that  $s(x, y; \omega)$  can be arbitrary for any  $x$  (i.e.  $\omega$  is  $d$ -dim)

$\rightarrow$  can do this using a universal kernel

$$s(\cdot, \cdot; \omega) \in \mathcal{H}_{X \times \mathbb{Y}}$$

### RKHS:

motivation for "kernel trick"



generalize linear structure

$\langle \omega, \phi(x) \rangle$  to higher dim. space

+ kernel trick  $\langle \phi(x), \phi(x') \rangle = k(x, x')$

$$\Phi: X \rightarrow \mathbb{R}^3$$

$$\Phi(x) = \begin{pmatrix} x_1^2 \\ \sqrt{2}x_1x_2 \\ x_2^2 \end{pmatrix}$$

$$\langle \Phi(x), \Phi(x') \rangle_{\mathbb{R}^3} = (\langle x, x' \rangle_{\mathbb{R}^2})^2 = (x_1x'_1 + x_2x'_2)^2 = k(x, x')$$

polynomial kernel e.g.  $(\langle x, x' \rangle + 1)^p = \tilde{k}(x, x')$

equivalent to mapping data to a space of dimension exponential in p

equivalent to mapping data to a space of dimension exponential in  $P$

$$\langle \Phi(x), \Phi(x') \rangle$$

even have to do this e.g.  $k(x, x') = \exp\left(-\frac{\|x - x'\|^2}{2}\right)$   
 "RBF kernel"

RKHS (reproducing kernel Hilbert space)

$\Phi: X \rightarrow \mathcal{H}$  s.t.  $\langle \Phi(x), \Phi(x') \rangle_{\mathcal{H}} = k(x, x')$  (important property of RKHS)

$\mathcal{H}$  is a space of fct.  $X \rightarrow \mathbb{R}$

let  $\tilde{\mathcal{H}} = \text{span} \{k(x, \cdot) : x \in X\}$  (here  $\Phi(x) = k(x, \cdot)$ ,

e.g.  $f \in \tilde{\mathcal{H}} \Rightarrow f = \sum_i \alpha_i k(x_i^f, \cdot)$  for some finite  $\{x_i\}_{i=1}^n$   $\alpha_i \in \mathbb{R}$

"pre-Hilbert" space [inner product space]

with  $\langle f, g \rangle_{\tilde{\mathcal{H}}} \triangleq \sum_{i,j} \alpha_i \alpha_j k(x_i^f, x_j^g)$

$$\|f\|_{\tilde{\mathcal{H}}} \triangleq \sqrt{\langle f, f \rangle_{\tilde{\mathcal{H}}}}$$

$$\langle k(x_i^f, \cdot), k(x_j^g, \cdot) \rangle_{\tilde{\mathcal{H}}}$$

then RKHS  $\mathcal{H}$  is = completion( $\tilde{\mathcal{H}}$ ) using  $\|\cdot\|_{\tilde{\mathcal{H}}}$  as your norm

i.e. add all limit points of  $\tilde{\mathcal{H}}$ -Cauchy sequences to get  $\mathcal{H}$

you could think  $f = \sum_{i=1}^{\infty} \alpha_i k(x_i, \cdot)$

⊗ "reproducing" property of  $\mathcal{H}$ :  $\forall f \in \mathcal{H}$

$$\langle f, k(x, \cdot) \rangle_{\mathcal{H}} = f(x)$$

$\Phi(x) \quad \leftarrow \quad \langle w, \Phi(x) \rangle$

nice property of RKHS, fct. evaluation is a c.b. operation.

mapping  $E_x: \mathcal{H} \rightarrow \mathbb{R}$   
 $E_x(f) = f(x)$

$$|f(x) - g(x)| = |\langle f - g, k(x, \cdot) \rangle_{\mathcal{H}}|$$

$$\leq \|f - g\|_{\mathcal{H}} \|k(x, \cdot)\|_{\mathcal{H}} \quad \text{i.e. } E_x \text{ is Lipschitz with } L = \|k(x, \cdot)\|_{\mathcal{H}}$$

⊗ this property is important to do statistics