

Lecture 13 - scribbles

Friday, October 18, 2019 13:57

- today:
 - undirected graph model
 - inference

undirected GM (UGM) (a.k.a. Markov random field or Markov network)

Let $G = (V, E)$ be an undirected graph

let \mathcal{C} be the set of cliques of G clique = fully connected set of nodes

(i.e. $C \in \mathcal{C} \Leftrightarrow \forall i, j \in C, \{i, j\} \in E$)



UGM associated with G

$$\mathcal{P}(G) \triangleq \left\{ p : p(x_v) = \frac{1}{Z} \prod_{C \in \mathcal{C}} \psi_C(x_C) \right\}$$

for some "potentials" ψ_C s.t. $\psi_C(x_C) \geq 0 \forall x_C$

and $Z \triangleq \sum_{x_v} \left(\prod_{C \in \mathcal{C}} \psi_C(x_C) \right)$ "partition function"

$$\sum_{x_1} \sum_{x_2} \dots \sum_{x_n}$$

Note: • unlike in DGM (where we could think of C to be (i, π_i) , $\psi_C(\pi_i) = p(\pi_i | x_m)$)

$\psi_C(\pi_i)$ is not directly related to $p(x_C)$

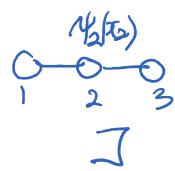
- can rescale any potential without changing p i.e. $\psi_C^{\text{new}}(\pi_i) \triangleq \psi_C^{\text{old}}(\pi_i) \cdot c$ $c > 0$
- it is sufficient to consider \mathcal{C}_{\max} , the set of maximal cliques

e.g. $C' \subseteq C$

$$\text{redefine } \psi_C^{\text{new}}(\pi_i) = \psi_C^{\text{old}}(\pi_i) \cdot \psi_{C'}^{\text{old}}(\pi_i)$$

(if C' belongs to more than one C , just choose one)

[we'll see later if it is convenient to ... , " ...]



consider "hyperparameterization" of trees
using both $\eta_i(x_i)$ and
 $\eta_{ij}(x_i, x_j)$

properties:

• as before, $E \subseteq E' \Rightarrow \mathcal{S}(G) \subseteq \mathcal{S}(G')$

$E = \emptyset \Rightarrow \mathcal{S}(G) = \text{fully factored dist.}$

$E = \text{all pairs}$ (i.e. G is just one big clique) $\mathcal{S}(G) = \text{all distributions}$

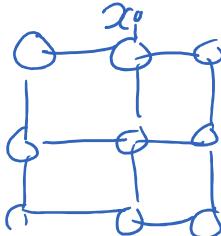
• if $\eta_c(x_c) > 0 \forall x_c$

$$\text{can write } p(x_v) = \exp\left(\sum_{c \in C} \log \eta_c(x_c) - \log Z\right)$$

phy s is link: negative energy function

e.g. Ising model in physics

$$x_i \in \{0, 1\}$$



node potential $\rightarrow E_i$
edge potential $\rightarrow F_{i,j}$

$$E_i = \eta_i(x_i=1)$$

$$E_{i,j} = \eta_{i,j}(x_i=1, x_j=1)$$

other example: social network modeling

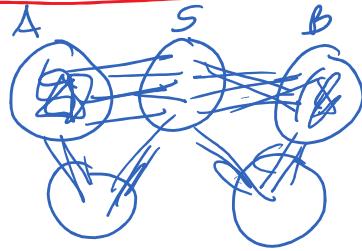
conditional independence for UGM

def: we say that p satisfies global Markov property (with respect to an undirected graph G)

if $A, B, S \subseteq V$ st. S separates A from B in G
disjoint

then $X_A \perp\!\!\!\perp X_B \mid X_S$

A S B



$$\begin{aligned} a &\in A \\ A &\subseteq V \\ C &\in \mathcal{C} \end{aligned}$$

prop:

$$p \in \mathcal{F}(G) \Rightarrow p \text{ satisfies the global Markov property for } G$$

proof:

wLOG, we assume $A \cup B \cup S = V \quad \nmid A \text{ separable from } B \text{ by } S$

[why? if not, let $\tilde{A} \triangleq A \cup \{a \in V : a \text{ and } A \text{ are not separated by } S\}$]

$$\tilde{B} \triangleq V \setminus (\tilde{A} \cup S)$$

then if we have $X_{\tilde{A}} \perp\!\!\!\perp X_B | X_S \Rightarrow X_A \perp\!\!\!\perp X_B | X_S$
by decomposition property

[exercise: show that if $b \in \tilde{B}$
 $\Rightarrow b$ separated from A by S]

$$V = A \cup S \cup B$$



Let $C \in \mathcal{C}$

cannot have $C \cap A \neq \emptyset$ and $C \cap B \neq \emptyset$

$$\text{thus } p(x) = \prod_{x_C} \prod_{\substack{C \in \mathcal{C} \\ C \subseteq A \cup S}} \Pr_{x_C} \Pr_{\substack{C' \in \mathcal{C} \\ C' \not\subseteq A \cup S}} = f(x_{A \cup S}) g(x_{B \cup S})$$

$\Rightarrow C \subseteq B \cup S$
and $C \not\subseteq S$

$$\begin{aligned} p(x_A | x_S) &\propto p(x_A, x_S) = \sum_{x_B} p(x_V) = \sum_{x_B} f(x_{A \cup S}) g(x_{B \cup S}) \\ &= f(x_{A \cup S}) \sum_{x_B} g(x_{B \cup S}) \\ &\Rightarrow p(x_A | x_S) = f(x_A, x_S) \end{aligned}$$

(constant with respect to x_A)

$$\Rightarrow p(x_A | x_S) = \frac{f(x_A, x_S)}{\sum_{x_A} f(x_A, x_S)}$$

constant with respect to x_A

$$\text{similarly, } p(x_B | x_S) = \frac{g(x_B, x_S)}{\sum_{x_B} g(x_B, x_S)}$$

$$p(x_A | x_S) p(x_B | x_S) = \frac{f(x_A, x_S) g(x_B, x_S)}{\sum_{x_A} \sum_{x_B} f(x_A, x_S) g(x_B, x_S)} \stackrel{?}{=} p(x_V) = p(x_A, x_B | x_S)$$

i.e. $x_A \perp\!\!\!\perp x_B | x_S$ //

thm: (Hammersley-Ciifford) $\Leftrightarrow p(x_V) > 0 \forall x_V$

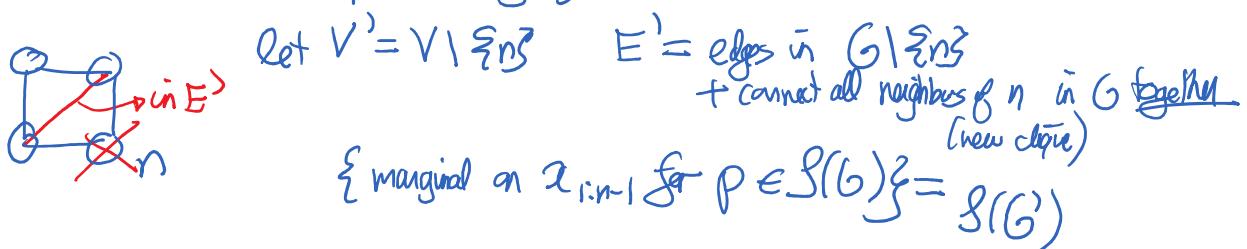
then $P \in \mathcal{S}(G) \Leftrightarrow P \underset{\text{Irc.}}{\text{satisfies the global Markov prop. for } G}$

proof: see ch. 16 of Mike's book ; use "Möbius inversion formula"

(as exclusion-inclusion principle in prob.)

more properties of UGM ..

* closure with respect to marginalization:



DGM vs UGM

def: Markov blanket for i (for graph G) is the smallest set of nodes M

st. $x_i \perp\!\!\!\perp X_V | X_M$

"rest"

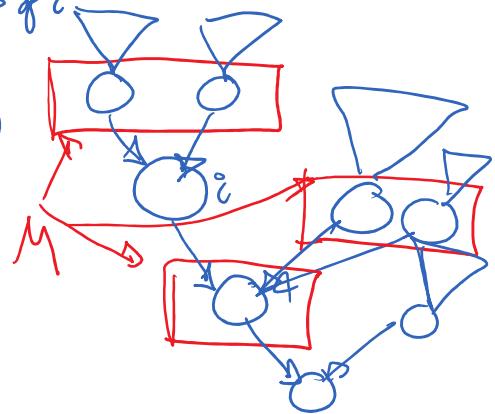
• for UGM: $M = \{j : \{i, j\} \in E\}$ - set of neighbors of i

... now $n \sim u_1, u_2, \dots, u_n$ s.t. $U = \{u_1, \dots, u_n\}$



• for UGM: $M = \{j\}$; $\exists i, j \in S \rightarrow$ set of neighbors of i

• for DGM: $M = \underbrace{\pi_i}_\text{like UGM} \cup \text{children}(i) \cup \bigcup_{j \in \text{children}(i)} \pi_j$



recap

	DGM	UGM
Factorization:	$p(x) = \prod_i p(x_i \pi_i)$	$\frac{1}{Z} \prod_i p(x_i)$
cond. indep.:	d-separation	separation
marginalization:	not closed in general e.g.	closed (connect all neighbors of removed node)
	<u>but is fine for loops</u>	
cannot exactly capture some families:		v-structure

Moralization:

Let G be a DAG; when can we transform to equivalent UGM

Def: for G a DAG, recall \overline{G} the moralized graph of G

where \overline{G} is an undirected graph with same V

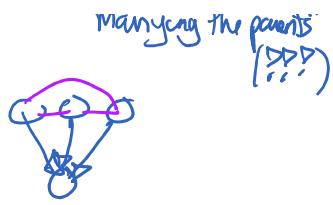
and $\overline{E} = \{ \{i,j\} : (i,j) \in E \} \quad \} \text{undirected version of } G$

$\cup \{ \{k,l\} : k \neq l \in \pi_i \text{ for some } i \} \quad \} \text{"moralization"}$

$\left(\begin{array}{l} \text{connect all the parents of } i \\ \text{with } i \text{ in big degree} \end{array} \right)$

"marrying the parents"

connect all the parents of i
with i in big degree
only needed when $|T_i| > 1$
i.e. V-structure



e.g.



prop: for a DAG G with no V-structure [first]

$$\text{then } \mathcal{S}(G) = \mathcal{S}(\bar{G})$$

DGM

UGM

but in general, can only say $\mathcal{S}_{\text{DGM}}(G) \subseteq \mathcal{S}_{\text{UGM}}(\bar{G})$

[note that \bar{G} is the minimal undirected graph s.t. $\mathcal{S}_{\text{DGM}}(G) \subseteq \mathcal{S}_{\text{UGM}}(\bar{G})$]

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general themes in this class

A) representation $\xrightarrow{\quad} \text{DGM}$
 $\xrightarrow{\quad} \text{UGM}$

parameterization \rightarrow exponential family

{ modeling
high dim. dist.

B) inference $p(z_Q | x_E)$ \rightarrow today's elimination alg.
"query" "evidence" \rightarrow next: sum-product belief propagation

C) statistical estimation / learning \rightarrow MLE
maximum entropy
method of moments

Inference:

present alg. for UGM [for simplicity and more generality]

but note that sometimes more efficient to ...

make DGM \rightarrow UGM via moralization

work with DGM directly

$$\text{ie. DGM : } p(x) = \prod_i p(x_i | z_{\pi_i}) \rightarrow \text{moralize: } C = \{\pi_i\} \cup \pi_i \\ = \frac{1}{Z} \prod_i N_C(z_i) \quad N_C(z_i) \triangleq p(x_i | z_{\pi_i}) \\ Z=1$$

inference: want to compute

a) marginal: $p(x_F)$ for some FSV

b) conditional: $p(x_F | x_E)$

"query" "evidence"

c) for UGM: partition function $Z = \sum_{x \in C \in \mathcal{G}} \prod_i N_C(x_i)$

why?

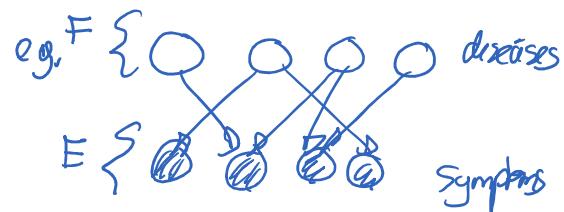
• missing data

$p(x_{\text{under}} | x_{\text{obs}})$

• prediction e.g. $p(x_{\text{future}} | x_{\text{past}})$

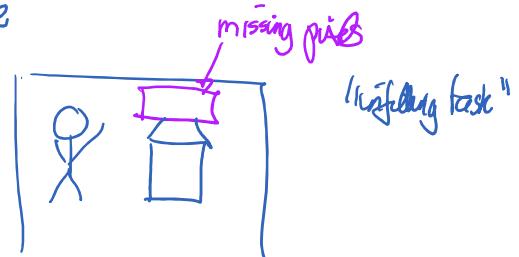
• "latent cause"

e.g. $p(x_{\text{cause}} | x_{\text{obs}})$



in vision

image



* also related to inference

augmar $p(x_F | x_E)$

Could be big hole (e.g. speech recognition)

* inference is also needed during estimation (parameter fitting MLE)
[e.g. during E-step $p(z|x)$]